




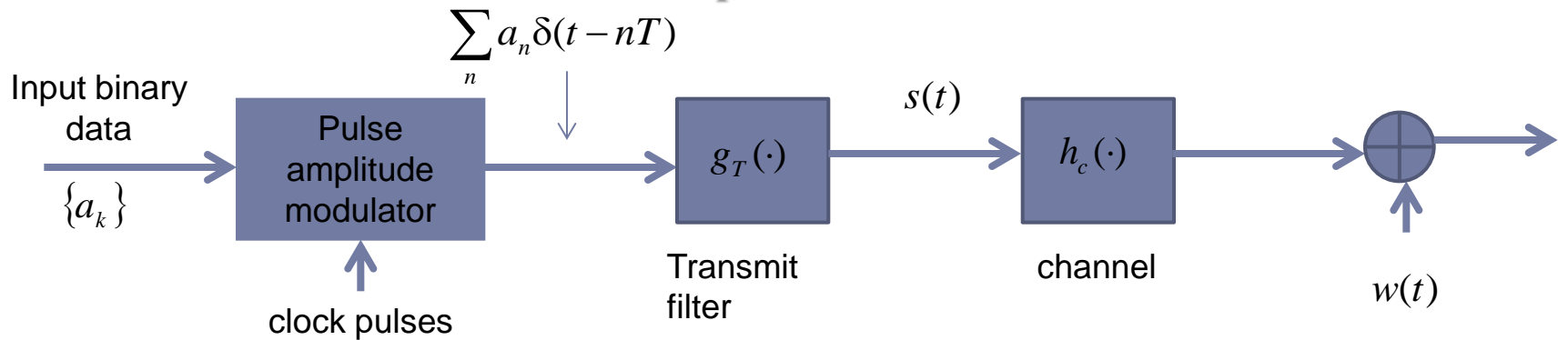
# Digital Communications Equalization



Dott.ssa Ernestina Cianca  
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# DIGITAL COMMUNICATION SYSTEM

## Optimal receiver

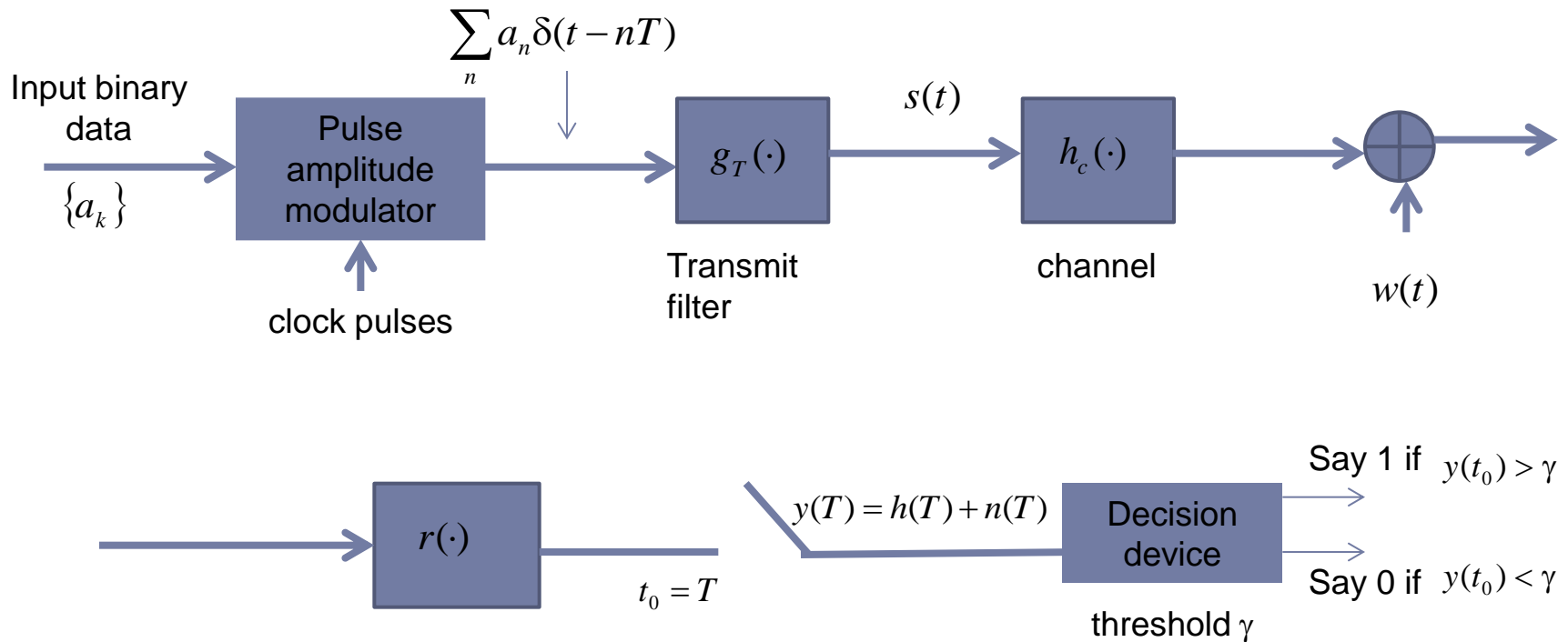


**Receiving filter** is essentially the demodulator, which recover the baseband pulse with the best possible signal-to-noise ratio.

**Equalizing filter** is an optional block needed in those systems where the channel-induced ISI can distort the signal

# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI



$\{a_k\}$  Stationary with autocorrelation  $\alpha_m = E[a_n a_{n+m}]$

$w(t)$  Stationary with zero mean and power spectral density  $|Q(f)|^2$

$\{a_k\}$   $w(t)$  Statistically independent

$h(t) = g_T(t) * h_c(t) * r(t)$  is assumed to be real (extension to the complex case can be done by the reader)

# DIGITAL COMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

Given  $G_T(f)$  and  $H_c(f)$  (we are assuming that the channel is KNOWN at the receiver....and time-invariant!!!!)

choose  $R(f)$

that minimizes the Mean Square Error (MSE)

$$MSE = E[(y_k - a_k)^2]$$

*Note: the real problem should be to minimize  $P[\hat{a}_k \neq a_k]$   
However, it is a very difficult problem and if  $E[(y_k - a_k)^2] \ll 1$  then  $y_k$  is very close to  $a_k$  in mean square sense and hence, in most of the cases it is possible to assume that the*

$$\mu(y_k) = \hat{a}_k \equiv a_k$$



# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

$$y_k = \sum_i a_i h((k-i)T) + w(kT) = \sum_i a_i h_{k-i} + w_k$$

$$\begin{aligned} MSE &= E[(y_k - a_k)^2] = E\left[\left(\sum_i a_i h_{k-i} + w_k - a_k\right)^2\right] \\ &= \sum_i \sum_j E[a_i a_j h_{k-i} h_{k-j}] + \sigma^2 + \alpha_0 + 2 \sum_i E[a_i h_{k-i} w_k] - 2 \sum_i E[a_i h_{k-i} a_k] - 2 \sum_i E[w_k a_k] \end{aligned}$$



$$MSE = \sigma^2 + \alpha_0 + \sum_i \sum_j \alpha_{i-j} h_{k-i} h_{k-j} - 2 \sum_i \alpha_{k-i} h_{k-i}$$

$$p = k - i, q = k - j$$



$$MSE = \sigma^2 + \alpha_0 + \sum_p \sum_q \alpha_{p-q} h_p h_q - 2 \sum_i \alpha_p h_q$$



# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

Going in the frequency domain

$$M(f) = \sum_i \alpha_i e^{-j2\pi i T}$$

$$U(f) = G_T(f)H_c(f)$$

being real

$$h_k = \int_{-\infty}^{\infty} H(f) e^{j2\pi f k T} df$$



$$h_k = \int_{-\infty}^{\infty} H^*(f) e^{-j2\pi f k T} df$$

$$\sigma^2 = \int_{-\infty}^{\infty} |Q(f)|^2 |R(f)|^2 df = \int_{-\infty}^{\infty} |Q(f)|^2 \frac{|H(f)|^2}{|U(f)|^2} df$$

$$\sum_p \sum_q \alpha_{p-q} h_p h_q = \sum_p \sum_q \alpha_{p-q} \int_{-\infty}^{\infty} H^*(f) e^{-j2\pi f p T} df h_q$$

$$= \int_{-\infty}^{\infty} H^*(f) \sum_q \left( \sum_p \alpha_{p-q} e^{-j2\pi f p T} \right) h_q df$$

$$= \int_{-\infty}^{\infty} H^*(f) \sum_q M(f) e^{-j2\pi f q T} h_q df$$

$$= \int_{-\infty}^{\infty} H^*(f) M(f) \frac{1}{T} \sum_l H\left(f - \frac{l}{T}\right) df$$

$$-2 \sum_p \alpha_p h_p = -2 \sum_p \alpha_p \int_{-\infty}^{\infty} H^*(f) e^{-j2\pi f p T} df$$

$$= -2 \int_{-\infty}^{\infty} H^*(f) M(f) df$$

# DIGITAL COMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

Let us summarize

$$MSE = \int_{-\infty}^{\infty} |Q(f)|^2 \frac{|H(f)|^2}{|U(f)|^2} df + \alpha_0 + \frac{1}{T} \int_{-\infty}^{\infty} M(f) H^*(f) \sum_l H\left(f - \frac{l}{T}\right) df$$

$$- 2 \int_{-\infty}^{\infty} M(f) H^*(f) df$$

Given  $U(f)$

$$\min_{R(f)} MSE = \min_{H(f)=R(f)U(f)} MSE$$

$$\text{con } H_{\text{opt}}(f): \frac{\partial MSE}{\partial H(f)} = 0$$

$$\text{siccome } \frac{\partial MSE}{\partial H(f)} = 2 \frac{|Q(f)|^2}{|U(f)|^2} H(f) + \frac{2}{T} M(f) \sum_l H\left(f - \frac{l}{T}\right) - 2M(f) = 0$$

Product of  
periodic terms  
of  $1/T$

periodic term of  
 $1/T$

# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI



$$G(f) \triangleq \frac{|Q(f)|^2}{|U(f)|^2} H(f) \quad \text{Must be a periodic function of } 1/T$$

Condition of optimum:

$$G(f) + \frac{1}{T} M(f) \sum_l \underbrace{G\left(f - \frac{l}{T}\right)}_{G(f)} \frac{\left| \frac{U\left(f - \frac{l}{T}\right)}{Q\left(f - \frac{l}{T}\right)} \right|^2}{G(f)} - M(f) = 0$$

Since it is  
periodic....therefore, I  
can bring it outside the  
sum





# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

Solution

$$G(f) = \frac{M(f)}{1 + M(f) \frac{1}{T} \sum_l \left| \frac{U\left(f - \frac{l}{T}\right)}{Q\left(f - \frac{l}{T}\right)} \right|^2}$$

SO:

$$H_{opt}(f) = G(f) \frac{|H(f)|^2}{|Q(f)|^2}$$

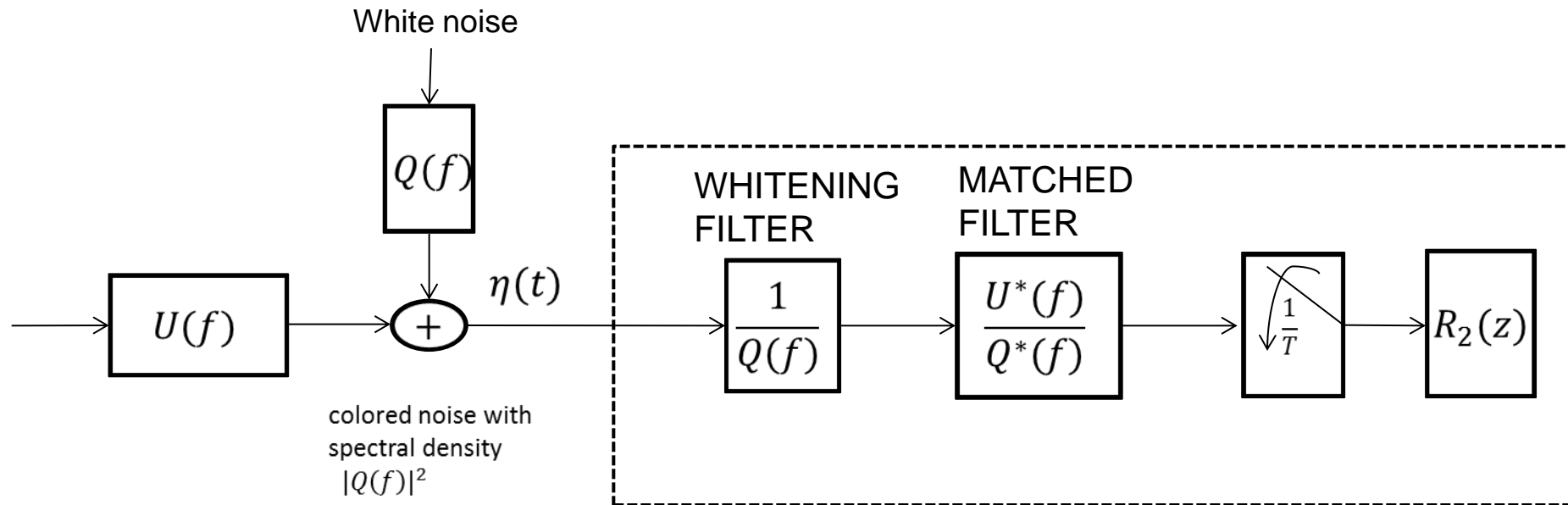
Fundamental result

$$R_{opt}(f) = \frac{H(f)}{U(f)} = \underbrace{\frac{U^*(f)}{|Q(f)|^2}}_{R_1(f)} \underbrace{\frac{M(f)}{1 + M(f) \frac{1}{T} \sum_l \left| \frac{U\left(f - \frac{l}{T}\right)}{Q\left(f - \frac{l}{T}\right)} \right|^2}}_{R_2(e^{j2\pi fT})}$$

$$R_2(e^{j2\pi fT})$$

# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI



# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

Hypothesis: white noise  $\Rightarrow |Q(f)|^2 = N_0$  constant

Let us define

$$\Phi(e^{j2\pi fT}) = \sum_p \varphi(pT) e^{-j2\pi f pT}$$

where

$$\varphi(t) = \int_{-\infty}^{\infty} u(x)u(x+t)dx \quad \text{Autocorrelation of the pulse } u(t)$$

$$U(f) = F[u(t)] \Rightarrow \Phi(e^{j2\pi fT}) = \frac{1}{T} \sum_l \left| U\left(f - \frac{l}{T}\right) \right|^2$$



$$R_{opt}(f) = U^*(f) \frac{M(f)}{N_0 + M(f)\Phi(e^{j2\pi fT})}$$

matched  
filter

$$R_2(e^{j2\pi fT})$$



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## Optimum linear receiver in presence of noise and ISI

Let us simplify  $R_2(e^{j2\pi fT})$

It is a periodic function, so we can write the Fourier series:

$$R_2(e^{j2\pi fT}) = \sum_{n=-\infty}^{\infty} c_n e^{-j2\pi f n T}$$

$$c_n = \frac{1}{T} \int_{-\infty}^{\infty} R_2(e^{j2\pi fT}) e^{j2\pi f n T} df$$

Let us truncate it up to the N most significant terms:

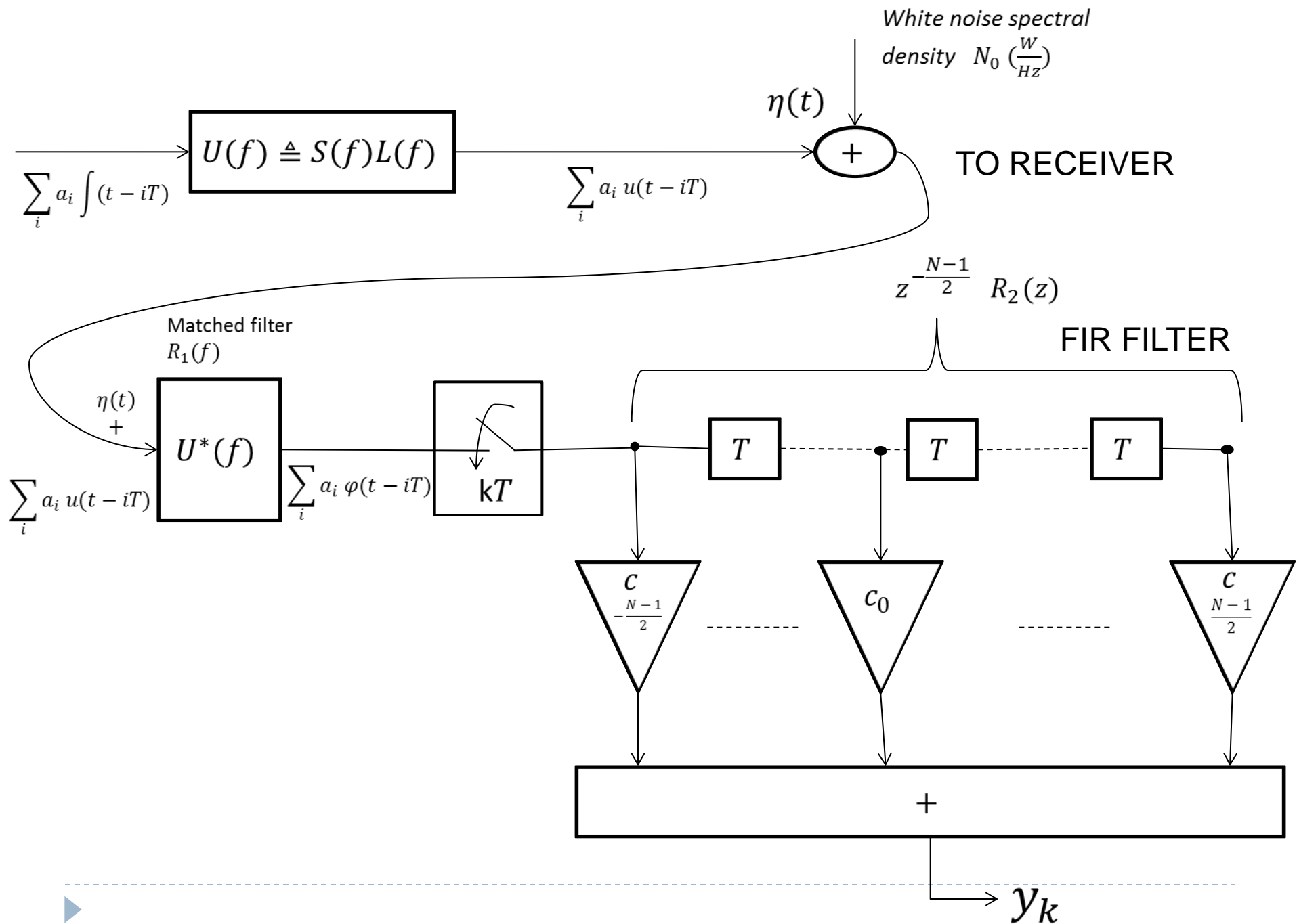
$$R_2(e^{j2\pi fT}) \approx \sum_{n=-\frac{N-1}{2}}^{\frac{N-1}{2}} c_n e^{-j2\pi f n T}$$



$$R_2(z) \approx \sum_{n=-\frac{N-1}{2}}^{\frac{N-1}{2}} c_n z^{-n}$$

Transfer function of a FIR filter  
which introduce a delay of N-1/2





# DIGITAL COMMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI


Let us consider two specific cases

1) Uncorrelated zero mean symbols  $M(f) = \alpha_0$

$$R_{opt}(f) = U^*(f) \frac{\alpha_0}{N_0 + \alpha_0 \Phi(e^{j2\pi fT})}$$

In low noise conditions, i.e.  $\frac{\alpha_0}{N_0} \gg 1$

$$R_2(e^{j2\pi fT}) \approx \frac{1}{\Phi(e^{j2\pi fT})} \Rightarrow R_2(e^{j2\pi fT}) \underbrace{\Phi(e^{j2\pi fT})}_{\text{Transform of the fundamental pulse after sampling before } R_2} = \cos t.$$

 Transform of the fundamental pulse after sampling before R2

The effect of  $R_2$  is to force the ISI to zero after the matched filter


$R_2$  is called **EQUALIZER**

▶ On the other hand, for moderate noise, there is always some ISI if we use the MSE criterion

# DIGITAL COMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

Moreover, always in case 1), if  $\varphi(t)$  satisfies the Nyquist criteria


$$\varphi(iT) = \varphi(0)\delta(iT) \Rightarrow \Phi(e^{j2\pi fT}) = \varphi(0)$$



$$R_2(e^{j2\pi fT}) = \frac{\alpha_0}{N_0 + \alpha_0\varphi_0} = \text{const.}$$



No equalization is needed



# DIGITAL COMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

2) Correlated zero mean symbols  $M(f) \neq \alpha_0$

3) Nyquist criterion for the pulse  $\varphi(iT) = \varphi(0)\delta(iT) \Rightarrow \Phi(e^{j2\pi fT}) = \varphi(0)$



The equalizer is needed

$$R_2(e^{j2\pi fT}) = \frac{M(f)}{N_0 + \alpha_0 M(f)}$$



The correlation introduces some ISI to compensate the noise  
Correlation is used to reduce the effect of noise





# DIGITAL COMUNICATION SYSTEM

## Optimum linear receiver in presence of noise and ISI

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# DIGITAL COMUNICATION SYSTEM

## Alternative Derivation of the optimum MSE receiver in presence of noise and ISI

### Hypothesis

1) White noise with power spectral density

2)  $R_1(f) = U^*(f)$

3)  $E[a_i a_j] = \alpha_0 \delta_{ij}, \quad E[a_i \eta_k] = 0 \quad \forall i, k$

The frequency response to the fundamental pulse in the decision point is:

$$|U(f)|^2 \xleftrightarrow{F^{-1}} \varphi(t) \quad (\text{autocorrelation of the pulse } u(t))$$

The power spectral density of the noise just before sampling is:

$$N_0 |U(f)|^2$$



# DIGITAL COMMUNICATION SYSTEM

## Alternative Derivation of the optimum MSE receiver in presence of noise and ISI

The autocorrelation of the sampled process  $x_k = \sum_i a_i \varphi_{k-i} + n_k$

is given by:

$$R_x(m) = E[x_{k+m} x_k^*] = \underbrace{\alpha_0 \sum_n \varphi_{n+m} \varphi_n^*}_{\text{autocorrelation of the sampled PAM signal}} + \underbrace{N_0 \varphi_m}_{\text{autocorrelation of the sampled noise}}$$

The correlation between  $x_k$  and  $a_k$

$$V(m) = E[a_{k+m} x_k^*] = \sum_i E[a_{k+m} a_i^*] \varphi_{k-i}^* + E[a_{k+m} n_k^*] = \alpha_0 \varphi_{-m}^*$$

# DIGITAL COMMUNICATION SYSTEM

## MSE algorithm

$$J = E[e_k^2] = E[y_k - a_k]^2 = E \left[ \left| \sum_{j=-\frac{N-1}{2}}^{\frac{N-1}{2}} c_j x_{k-j} - a_k \right|^2 \right]$$

$$\boxed{\frac{\partial J}{\partial c_l} = 0}$$



$$2E[(y_k - a_k)x_{k-l}^*] = 0$$



$$\sum_{j=-\frac{N-1}{2}}^{\frac{N-1}{2}} c_j E[x_{k-j}x_{k-l}^*] = E[a_k x_{k-l}^*]$$

$R_x(l-j) \qquad V(l)$



$$\sum_{j=-\frac{N-1}{2}}^{\frac{N-1}{2}} c_j [\alpha_0 R_\varphi(l-j) + N_0 \varphi_{l-j}] = \alpha_0 \varphi_{-l}^*$$



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## MSE algorithm

Let us consider the case of an ideal equalizer  $N \rightarrow \infty$

Denoting with  $\Phi(z) = Z[\varphi_n]$



The previous equation can be written in terms of zeta-transforms as follows:

$$C(z) \left[ \alpha_0 \Phi(z) \Phi^* \left( \frac{1}{z} \right) + N_0 \Phi(z) \right] = \alpha_0 \Phi^* \left( \frac{1}{z} \right)$$

$\varphi_k$  is an autocorrelation function  is Hermitian  $\varphi_k = \varphi_{-k}^*$



$$\Phi(z) = \Phi^* \left( \frac{1}{z^*} \right)$$



# DIGITAL COMUNICATION SYSTEM

## MSE algorithm

$$C(z)[\alpha_0\Phi(z) + N_0] = \alpha_0$$



$$C_{opt}(z) = \frac{\alpha_0}{\alpha_0\Phi(z) + N_0}$$

